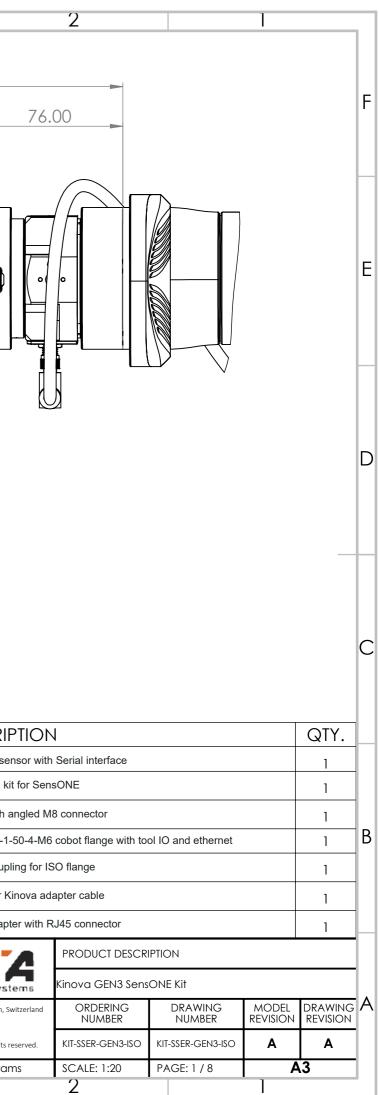
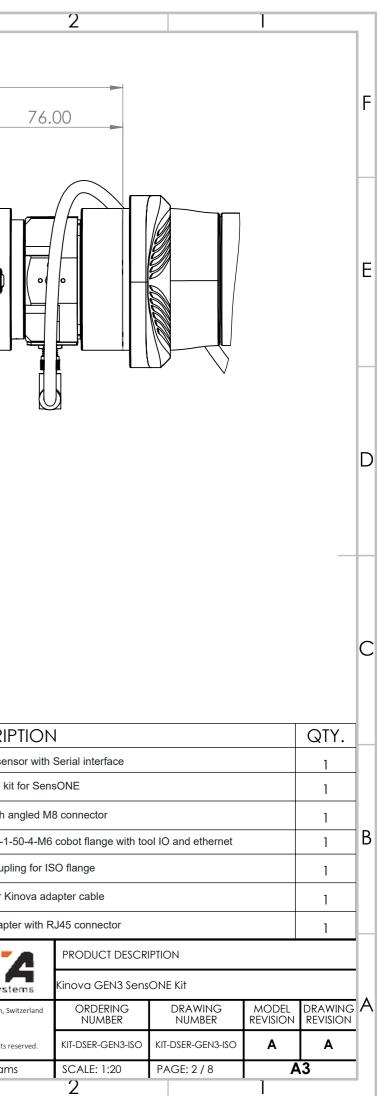
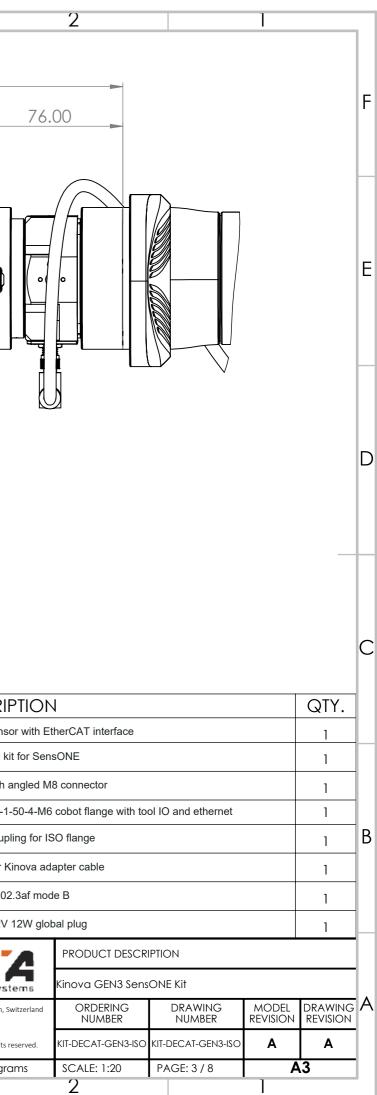
Г	8	7	6		5	4		3
F							Ā	222.2
E		2			3	ſ		
D	(a) +			4				
С								
			l	TEM NO.	ORDERING	NUMBER		DESCRIF
		$\langle \rangle$	-	1	BFT-SENS-SER-M8			SensONE T15 6-axis F/T ser
				2	ACC-SENS-MOUNT			Screw mounting kit
В				3	ACC-RJ45-M8-3M-ANGL	.E		3.0m Cat 5e cable with a
			-	4	ACC-KIN-GEN3		Ac	cessory adapter for Kinova Gen3 to ISO 9409-1-
			-	5	RQ-GRP-ES-CPL-062			Robotiq Gripper coupli
			-	6	ACC-KIN-GEN3-BUMP			Protective bumper for Ki
					ACC-USB-PROG			USB to RS422 Serial adapte
A	 Properly place the adapter (A the opposite side from where Use the screws included on th Place the Bota FT sensor on ta Continue by adding the robo the adapter on the same side Finally, add the gripper, make 	to the Gen3 robotic arm using the flex cable SS-KIN-GEN3) on the robotic arm, making su the camera of the robot is located. e accesory to properly attach the adapter. p using the correct mount (ACC-SENS-MOU tic gripper adapter (RQ_GRP-ES-CPL-062), m as the Kinova adapter ACC-KIN-GEN3) for t sure to use the recommended screws and	In the place the connector face on NT), which includes screws and the pin. Taking sure to have the cable side of the cable to be connected straight. pins.	NOTES				Hagenholzstrasse 85, 8050, Zurich, Sw Email: info@botasys.com Website: www.botasys.com @2022 BOTA Systems AG. All rights re WEIGHT 897 gram
	8	7	6		5	4		3



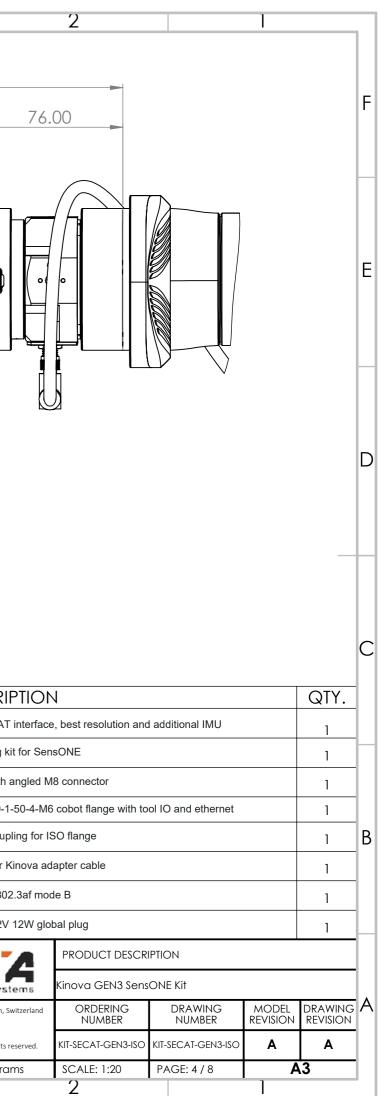
Γ	8	7	6		5	4		3	
F								222.2	
E	5				3	Ē			Ð
D				(4)		Ę			
С			F						
			_	ITEM NO.	ORDERING	NUMBER		DESC	
			-	1	BFT-DENS-SER-M8			SensONE T5 6-axis F/T	
		•		2	ACC-SENS-MOUNT			Screw mountin	
В				3	ACC-RJ45-M8-3M-ANGL	.E		3.0m Cat 5e cable w	
			-	4	ACC-KIN-GEN3		Acc	cessory adapter for Kinova Gen3 to ISO 940	
			-	5	RQ-GRP-ES-CPL-062			Robotiq Gripper co	
			-	6	ACC-KIN-GEN3-BUMP			Protective bumper fo	
┢					ACC-USB-PROG			USB to RS422 Serial ac	laapte
A	 Properly place the adapter (ASS the opposite side from where th Use the screws included on the Place the Bota FT sensor on top Continue by adding the robotic the adapter on the same side a Finally, add the gripper, make successful to the same side a 	the Gen3 robotic arm using the flex cable S-KIN-GEN3) on the robotic arm, making so e camera of the robot is located. accesory to properly attach the adapter. using the correct mount (ACC-SENS-MOU gripper adapter (RQ_GRP-ES-CPL-062), n s the Kinova adapter ACC-KIN-GEN3) for ure to use the recommended screws and	ure to place the connector face on INT), which includes screws and the pin. naking sure to have the cable side of the cable to be connected straight.	NOTES				Hagenholzstrasse 85, 8050, Zuri Email: info@botasys.com Website: www.botasys.com @2022 BOTA Systems AG. All rig WEIGHT 897 gt	rights re:
	8	7	6		5	4		3	



B 1 BFT-DENS-ECAT-M8 SensONE T5 6-axis F/T sensor 2 ACC-SENS-MOUNT Screw mounting kit 3 ACC-RIA-SM8-3M-ANGLE 3.0m Cat 5e cable with a 4 ACC-KIN-GEN3 Accessory adapter for Kinova Gen3 to ISO 9409-1- 5 RQ-GRP-ES-CPL-062 Robotiq Gripper coupl 6 ACC-KIN-GEN3-BUMP Protective bumper for Kinova Gen3 to ISO 9409-1- 8 ACC-POE-B PoE injector 802 9 ACC-PSU-12V-GLOBAL Power adapter 12V MOUINING STEPS NOTES 1 Connect the Kinova adapter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3	Г	8	7	6		5	4		3	
B Image: Constraint of the constraint	F						-		222.	2
C Image: Control integration of the Contrel integration of the Control integration	E					3	Ę			2F Adaptive Gripper
C Image: Constraint of the constaint of the constaint of the constraint of	D	-								
B Image: Constraint of the consthe constraint of the constraint of the con	С				ITEM NO.		NUMBER		SensONE T5 6-	DESCRIF -axis F/T senso
B 3 ACC-RI45-M8-3M-ANGLE 3.0m Cat 5e cable with a 4 ACC-KIN-GEN3 Accessory adapter for Kinova Gen3 to ISO 9409-1- 5 RQ-GRP-ES-CPL-062 Robotiq Gripper couple 6 ACC-KIN-GEN3-BUMP Protective bumper for Kinova 8 ACC-POE-B Pole injector 802 9 ACC-POE-B Power adapter 12V 9 ACC-POE-B Power adapter 12V 1. Connect the Kinova dopter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3 NOTES 1. Connect the Kinova dopter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3 NOTES 1. Connect the Kinova dopter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3 NOTES 1. Connect the Kinova dopter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3 NOTES 1. Connect the Kinova dopter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3 NOTES 1. Connect the Kinova dopter to the Gen3 robotic arm using the flex coble included on the ACC-KIN-GEN3 NOTES 1. Connect the Kinova dopter to the dopter. NOTES Notes the Start is call on the concet dopter ACC-KIN-GEN3 (red to adopter ACC-KIN-GEN3) Notes the stort is c					2	ACC-SENS-MOUNT			Scre	ew mounting kit
B 4 ACC-KIN-GEN3 Accessory adapter for Kinova Gen3 to ISO 9409-1- 5 RQ-GRP-ES-CPL-062 Robotiq Gripper couple 6 ACC-KIN-GEN3-BUMP Protective bumper for Kinova 8 ACC-POE-B PoE injector 802 9 ACC-PSU-12V-GLOBAL Power adapter 12V 8 ACC-PSU-12V-GLOBAL Power adapter 12V 9 ACC-PSU-12V-GLOBAL Power adapter 12V 8 ACC-PSU-12V-GLOBAL Power adapter 12V 9						ACC-RJ45-M8-3M-ANGL	E		3.0m Cat	5e cable with a
B 5 RQ-GRP-ES-CPL-062 Robotig Gripper couple 6 ACC-KIN-GEN3-BUMP Protective bumper for Ki 8 ACC-POE-B PoE injector 802 9 ACC-PSU-12V-GLOBAL Power adapter 12V 8 Property place the adapter (ASS-KIN-GEN3) on the robotic arm, making sure to place the connector face on the opposite side from where the camera of the roboti s located. NOTES 1 Connect the Kinova adapter (ASS-KIN-GEN3) on the robotic arm, making sure to place the connector face on the opposite side from where the camera of the roboti s located. NOTES 3 Use the screws included on the accessry. Hagenhoiztrasse 55, 8050, Zuich, 5% 5 Confinue by adding the robotis (accrew on the ocabe size, connected straight. Hagenhoiztrasse 55, 8050, Zuich, 5% 5 Confinue by adding the robotis (accrew on the ocabe) size of the cadapter. Hagenhoiztrasse 55, 8050, Zuich, 5% 6 Finally, add the gripper, make sure to use the recommended screws and pins. WEIGHT 1020 grad						ACC-KIN-GEN3		Acce	essory adapter for Kinova Gen3	to ISO 9409-1-
MOUNTING SIEPS 9 ACC-POE-B Poet injector 802 9 ACC-PSU-12V-GLOBAL Power adapter 12V 9 ACC-PSU-12V-GLOBAL </td <th>В</th> <td></td> <td></td> <td></td> <td>5</td> <td>RQ-GRP-ES-CPL-062</td> <td></td> <td></td> <td>Robotic</td> <td>g Gripper coupli</td>	В				5	RQ-GRP-ES-CPL-062			Robotic	g Gripper coupli
A C-PSU-12V-GLOBAL Power adapter 12 9 ACC-PSU-12V-GLOBAL Power adapter 12 MOUNTING STEPS 1. Connect the Kinova adapter to the Gen3 robotic arm using the flex cable included on the ACC-KIN-GEN3 Properly place the adapter (ASS-KIN-GEN3) on the robotic arm, making sure to place the connector face on the opposite side from where the camera of the robot is located. 3. Use the screws included on the accessory to properly attact the adapter. 4. Place the Bota FI sensor on top using the correct mount (ACC-SENS-MOUNT), which includes screws and the pin. 5. Continue by adding the robotic gripper adapter (RQ_GRP-ES-CPL-062), making sure to have the cable side of the adapter on the same side as the Kinova adapter ACC-KIN-GEN3 for the cable to be connected straight. 6. Finally, add the gripper, make sure to use the recommended screws and pins. WEIGHT 1020 grad			Ĩ		6	ACC-KIN-GEN3-BUMP			Protective	e bumper for Ki
 A MOUNTING STEPS Connect the Kinova adapter to the Gen3 robotic arm using the flex cable included on the ACC-KIN-GEN3 Properly place the adapter (ASS-KIN-GEN3) on the robotic arm, making sure to place the connector face on the opposite side from where the camera of the robot is located. Use the screws included on the accessory to properly attach the adapter. Place the Bota FI sensor on top using the correct mount (ACC-SENS-MOUNT), which includes screws and the pin. Continue by adding the robotic gripper adapter (RQ_GRP-ES-CPL-062), making sure to have the cable side of the adapter on the same side as the Kinova adapter ACC-KIN-GEN3 for the cable to be connected straight. Finally, add the gripper, make sure to use the recommended screws and pins. 					8	ACC-POE-B			P	oE injector 802.
 Connect the Kinova adapter to the Gen3 robotic arm using the flex cable included on the ACC-KIN-GEN3 Properly place the adapter (ASS-KIN-GEN3) on the robotic arm, making sure to place the connector face on the opposite side from where the camera of the robot is located. Use the screws included on the accessory to properly attach the adapter. Place the Bota FT sensor on top using the correct mount (ACC-SENS-MOUNT), which includes screws and the pin. Continue by adding the robotic gripper adapter (RQ_GRP-ES-CPL-062), making sure to have the cable side of the adapter on the same side as the Kinova adapter ACC-KIN-GEN3) for the cable to be connected straight. Finally, add the gripper, make sure to use the recommended screws and pins. 					9	ACC-PSU-12V-GLOBAL			Powe	r adapter 12V 1
	A	 Connect the Kinova adapter Properly place the adapter (A the opposite side from where Use the screws included on th Place the Bota FT sensor on to Continue by adding the robot the adapter on the same side 	ASS-KIN-GEN3) on the robotic arm, makin the camera of the robot is located. The accesory to properly attach the adap op using the correct mount (ACC-SENS-A tic gripper adapter (RQ_GRP-ES-CPL-06) as the Kinova adapter ACC-KIN-GEN3)	ng sure to place the connector face on pter. MOUNT), which includes screws and the pin. 2), making sure to have the cable side of 1 for the cable to be connected straight.					Email: info@bol Website: www.l ©2022 BOTA Sy	tasys.com botasys.com /stems AG. All rights re
			7			5	4			1020 gra



8 7 6 5 4	3
F	222.2
	BINOBOTING
C 9 ITEM NO. ORDERING NUMBER	DESCRIF
	axis F/T sensor with EtherCAT i
2 ACC-SENS-MOUNT	Screw mounting kit
3 ACC-RJ45-M8-3M-ANGLE	3.0m Cat 5e cable with a
	for Kinova Gen3 to ISO 9409-1-
B 5 RQ-GRP-ES-CPL-062	
	Robotiq Gripper coupli
6 ACC-KIN-GEN3-BUMP	Robotiq Gripper coupli
	Robotiq Gripper coupli Protective bumper for Ki
6 ACC-KIN-GEN3-BUMP	Robotiq Gripper coupli Protective bumper for Ki PoE injector 802. Power adapter 12V 1
6 ACC-KIN-GEN3-BUMP 8 ACC-POE-B	Robotiq Gripper coupl Protective bumper for Ki PoE injector 802



	8		7		6		5	4			3	2			
F										Ø 63.00					F
D				4	3					\$31.50	Ø 5	0 6.00 6.05 X 90°			C
			766000				0.00.000								0.71
						TEM NO.	BFT-SENS-SER-M8	g number		c	DESCRIPTIC SensONE T15 6-axis F/T sensor w				QTY.
В					-	2	ACC-SENS-MOUNT				Screw mounting kit for Sc				<u> </u>
						3	ACC-RJ45-M8-3M-AN	GLE			3.0m Cat 5e cable with angled				
					-	4	ACC-KIN-GEN3		Ac	cessory adapter for K	Kinova Gen3 to ISO 9409-1-50-4-N		ol IO and ethernet		1
						7	ACC-USB-PROG			I	USB to RS422 Serial adapter with	RJ45 connector			1
1. 2. A 3. 4.	Properly place the adap the opposite side from v Use the screws included	lapter to the Gen3 robotion pter (ASS-KIN-GEN3) on the where the camera of the	ne robotic arm, makin robot is located. perly attach the adap	ng sure to place the o oter.	connector face on	NOTES					Beeirase Hagenholzstrasse 85, 8050, Zurich, Switzerland Email: info@botasys.com	PRODUCT DESCR Kinova GEN3 Sens ORDERING NUMBER		MODEL REVISION	DRAWING A
4.	TIGGE THE DOTA FT SENSO	ייסו וופ נסוופט ווופ correct	н поонт (ACC-JENJ-M	CONT, WHICH INCIUD	ica acrewa unu ine piñ.						Website: www.botasys.com ©2022 BOTA Systems AG. All rights reserved.	KIT-SSER-GEN3	KIT-SSER-GEN3	A	A
	8		7		6		5	4			WEIGHT 725 grams	SCALE: 1:20	PAGE: 5 / 8		3
	0		/		6		5	4		v	5	۷		1	

	8	/	6		5	4		3	2		
F							\$63.00				F
C		7					Ø31.50		 ✓ 6.00 ✓ 5.00 THRU ✓ 6.05 X 90° 		C
				ITEM N	BFT-DENS-SER-M8	IG NUMBER		DESCRIF SensONE T5 6-axis F/T ser			QTY.
В		-		2	ACC-SENS-MOUNT			Screw mounting ki			1B
				3	ACC-RJ45-M8-3M-AN	IGLE		3.0m Cat 5e cable with a			
				4	ACC-KIN-GEN3		Accessory adapte	er for Kinova Gen3 to ISO 9409-1-	50-4-M6 cobot flange with to	ool IO and ethernet	1
				7	ACC-USB-PROG			USB to RS422 Serial adapt	er with RJ45 connector		1
A ^{1.} 2. 3. 4.	Properly place the adapter (A the opposite side from where t Use the screws included on the Place the Bota FT sensor on top	SS-KIN-GEN3) on the robotic arm, the camera of the robot is located e accesory to properly attach the		I-GEN3 r face on	DIES			Hagenholzstrasse 85, 8050, Zurich, St Email: info@botasys.com Website: www.botasys.com ©2022 BOTA Systems AG. All rights r WEIGHT 725 grou	vitzerland ORDERING NUMBER served. KIT-DSER-GEN3	sONE Kit	MODEL DRAWING REVISION REVISION A A A3
	8	7	6		5	4		3	2		1

		8		7		6		5		4		3	2			
F		(1)					R				\$ 63.00					F
D					4	3					Ø31.50		90°			D
С		Ę	9									Ø 5.	<u>6.00</u> 00 THRU 6.05 X 90°			С
						[ITEM NO.	ORDERI	NG NUMBE	२		DESCRIPTIO	N		Q	TY.
							1	BFT-DENS-ECAT-N			Se	nsONE T5 6-axis F/T sensor with I				1
В				8		·	2	ACC-SENS-MOUN				Screw mounting kit for Se				1B
							3	ACC-RJ45-M8-3M-/ ACC-KIN-GEN3	ANGLE		According adapter for M	3.0m Cat 5e cable with angled I		ol IO and other - t		
							4	ACC-RIN-GEN3			Accessory adapter for K	(inova Gen3 to ISO 9409-1-50-4-M PoE injector 802.3af mo				
							8	ACC-PSU-12V-GLC	BAL			Power adapter 12V 12W gl				<u></u>
A	1. C 2. Pr th 3. U	Properly place the add he opposite side from Ise the screws include	dapter to the Gen3 rob pter (ASS-KIN-GEN3) o where the camera of t d on the accesory to p	n the robotic arm, mo he robot is located. roperly attach the ac	aking sure to place the	the ACC-KIN-GEN3 e connector face on ludes screws and the pin	NOTES					Hagenholzstrasse 85, 8050, Zurich, Switzerland Email: info@botasys.com @2022 BOTA Systems AG. All rights reserved. WEIGHT 843 grams	PRODUCT DESCR Kinova GEN3 Sens ORDERING NUMBER KIT-DECAT-GEN3 SCALE: 1:20		MODEL REVISION A A3	WING A
		8		7		6		5		4		3	2			

		8		7		6		5	4		3	8	2		1	
F											Ø 63.00					F
					4	3					Ø31.50		90°			D
C		-	9									Ø5	6.00 00 THRU 6.05 X 90°			C
						-	ITEM NO.	ORDERING	NUMBER	Sanco	NE T15 6 avia	DESCRIPTIO F/T sensor with EtherCAT interfac		additional IML	(QTY.
				8		-	2	ACC-SENS-MOUNT				Screw mounting kit for Se				1
B					1		3	ACC-RJ45-M8-3M-ANG	_E			3.0m Cat 5e cable with angled I				1 B
			R			-	4	ACC-KIN-GEN3 ACC-POE-B		Accessor	y adapter for Ki	nova Gen3 to ISO 9409-1-50-4-M PoE injector 802.3af mo		ol IO and ethernet		
			H			-	8	ACC-POE-B ACC-PSU-12V-GLOBAL				Power adapter 12V 12W gl				
А	1. 2. 3. 4.	MOUNTING STEPS Connect the Kinova adapt Properly place the adapte the opposite side from whe Use the screws included or Place the Bota FT sensor or	r (ASS-KIN-GEN3) on the ere the camera of the ro in the accesory to prope	e robotic arm, making obot is located. erly attach the adapt	g sure to place the ter.	connector face on	<u>NOTES</u>	1		1		Hagenholzstrasse 85, 8050, Zurich, Switzerland Email: info@botasys.com @2022 BOTA Systems AG. All rights reserved. WEIGHT 843 grams	PRODUCT DESCR Kinova GEN3 Sens		MODEL REVISION A A3	
L		8		7		6		5	4		3	}	2			